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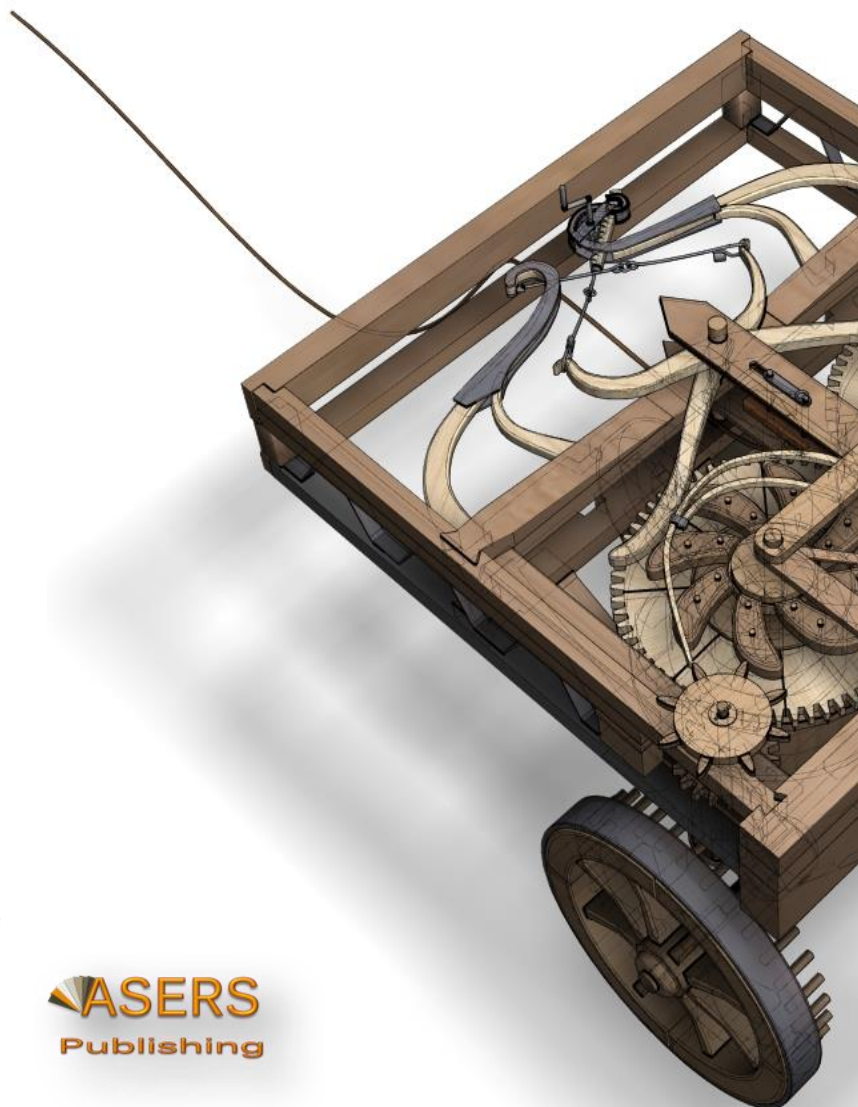
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DISCRETE TIME OR CONTINUOUS TIME, THAT IS THE QUESTION: THE CASE OF SAMUELSON'S MULTIPLIER-ACCELERATOR MODEL

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Abstract:

A basic problem in economic dynamics is the choice of continuous-time or discrete-time in mathematical modeling. In this paper, we study the continuous-time Samuelson's multiplier-accelerator model and compare this continuous-time model with its classical discrete-time model. We find that although time scales do not affect the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model, but time scales have an influence on the perfect symmetry of periodic motion.

Keywords: Samuelson's multiplier-accelerator model, time scales, perfect symmetry, probability, return to equilibrium

JEL Classification: B41, C02, E1, E2, E32, H5

1. Introduction

Measurement cannot be separated from theory. Theoretical thinking is better through a mathematical representation. The choice of mathematical representations depends on the essential features in empirical observation and theoretical perspective. A mathematical representation should be powerful enough to display stylized features to be explained and simple enough to manage its mathematical solution to be solved.

The choice of the kind of 'time' (continuous or discrete) to be used in the construction of dynamic models is a moot question. We know that such a choice implies the use of different analytical tools: differential equations in continuous time and difference equations in discrete time. In mathematical economics and econometrics, many models are in the forms of difference equations in discrete-time without much justification. There were only a few economists using continuous-time models.

Economists like use discrete-time models more than continuous-time model in economic modeling because, on the one hand, economic data are reported in terms of discrete-time such as annual data, seasonal data and monthly data, on the other hand, discrete-time model is easy to run regression. However, compared with discrete-time model, continuous-time models have different behavioral solutions and different stability conditions in nature.

In this paper, we study the continuous-time Samuelson's multiplier-accelerator model and compare this continuous-time model with its classical discrete-time model. We find that although time scales do not affect the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model, but time scales have an influence on the perfect symmetry of periodic motion.

The structure of the rest of the paper is as follows. In part 2, we give discrete-time Samuelson's multiplier-accelerator model. In part 3, we give continuous-time Samuelson's multiplier-accelerator model. In part 4 we give the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model. In part 5 we give a conclusion.

2. Discrete time Samuelson's multiplier-accelerator model

The original version of the Samuelson's multiplier-accelerator is in discrete time (Samuelson 1939):

$$C_t = aY_{t-1} \tag{1}$$

$$I_t = b(C_t - C_{t-1}) \tag{2}$$

$$Y_t = C_t + I_t + G \tag{3}$$

where C is consumption, I is investment, G is government expenditure, Y is income, and $0 < a < 1, b > 0$.

We have a second-order difference equation

$$Y_t - a(1+b)Y_{t-1} + abY_{t-2} = G \tag{4}$$

The model has five types of solutions:

- (1) Monotonically converging regime A and its borderline;
- (2) Damped oscillation regime B;
- (3) Explosive oscillation regime C;
- (4) Monotonically diverging regime D and its borderline;
- (5) Periodic oscillation curve PQ'.

We should notice that the periodic oscillation occurs only at the borderline between B and C regime, i.e. curve PQ'. Patterns in the parameter space are shown in Figure 1.

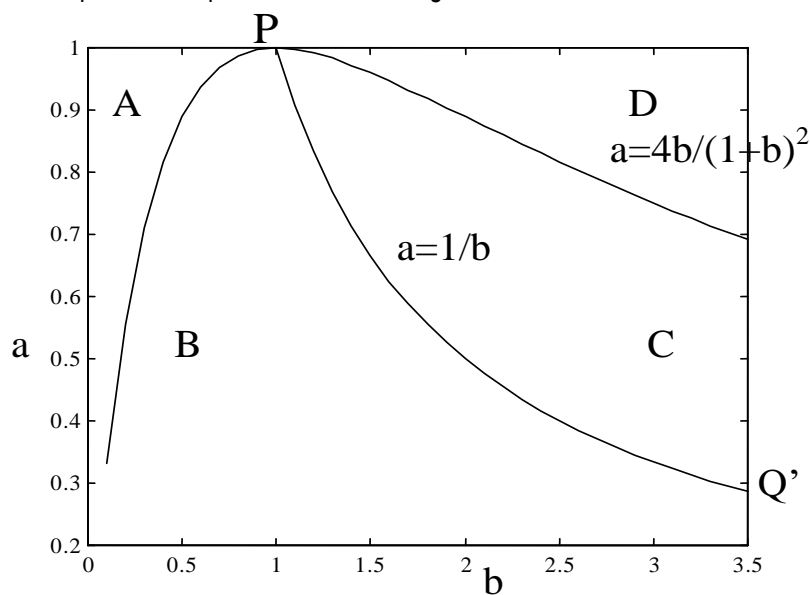


Figure 1. Discrete-time Samuelson's multiplier-accelerator diagram.

A and its borderline stands for monotonically converging; B, damped oscillation; PQ', periodic oscillation; C, explosive oscillation; D and its borderline, monotonically diverging.

3. Continuous time Samuelson's multiplier-accelerator model

We discuss the continuous time version of the above Samuelson's model to demonstrate the relation between discrete time and continuous time linear models.

We simply replace the difference by the derivative in the above Samuelson's model. We have

$$C(t) = aY(t-1) = a[Y(t) - (Y(t) - Y(t-1))] = a[Y(t) - Y'(t)] \tag{5}$$

$$I(t) = b[C(t) - C(t-1)] = ba[(Y(t) - Y'(t)) - (Y(t-1) - Y'(t-1))] = ba[Y'(t) - Y''(t)] \quad (6)$$

In (5), $Y(t) - Y'(t)$ stands for the correction of current income, so the consumption at time t , $C(t)$, can be regarded as linear function of the correction of the income at time t , $Y(t)$. In (6), $Y'(t) - Y''(t)$ stands for the correction of the change of current income, so the investment at time t , $I(t)$, can be regard as linear function of the correction of the change of the income at time t , $Y(t)$.

As a result, we have continuous time Samuelson's multiplier-accelerator model

$$C(t) = a[Y(t) - Y'(t)] \quad (5)$$

$$I(t) = ba[Y'(t) - Y''(t)] \quad (6)$$

$$Y(t) = C(t) + I(t) + G \quad (7)$$

We have a second-order differential equation

$$Y''(t) + \frac{1-b}{b}Y'(t) + \frac{1-a}{a*b}Y(t) = G/(a*b) \quad (8)$$

In (8), taking $Y''(t) = Y'(t) = 0$ we have equilibrium solution

$$Y(t) = G/(1-a) \quad (9)$$

The correspondent homogeneous equation of (8) is

$$Y''(t) + \frac{1-b}{b}Y'(t) + \frac{1-a}{a*b}Y(t) = 0 \quad (10)$$

The characteristic equation is

$$\lambda^2 + \frac{1-b}{b}\lambda + \frac{1-a}{a*b} = 0 \quad (11)$$

two roots of the characteristic equation are

$$\lambda_1 = (-b_1 + \sqrt{\Delta})/2$$

$$\lambda_2 = (-b_1 - \sqrt{\Delta})/2$$

where $b_1 = \frac{1-b}{b}b_1$, $\Delta = -b_1^2 - 4(1-a)/a*b$

A. When $\Delta > 0$, equation (11) have two different real roots and the general solutions of (8) are

$$Y(t) = C_1 \exp(\lambda_1 t) + C_2 \exp(\lambda_2 t) + G/(1-a)$$

If $b_1 > 0$, i.e. $1 > b$, λ_1, λ_2 are all negative roots and the solutions are monotonically converging.

If $b_1 < 0$, i.e. $1 < b$, λ_1, λ_2 are all positive roots and the solutions are monotonically diverging.

If $b_1 = 0$, $\Delta = -4(1-a)/(ba) < 0$ (for $0 < a < 1$, $b > 0$), so $b_1 = 0$ is impossible.

B. When $\Delta = 0$, equation (11) have two same real roots and the general solutions of (8) are

$$Y(t) = (C_1 + C_2 t) \exp(-t b_1 / 2) + G/(1-a)$$

If $b_1 > 0$, i.e. $1 > b$, the solutions are monotonically converging.

If $b_1 < 0$, i.e. $1 < b$, the solutions are monotonically diverging.

If $b_1 = 0$, i.e. $1 = b$, $a = 1$, but $0 < a < 1$, so $b_1 = 0$ is impossible.

When $\Delta < 0, \lambda_1, \lambda_2 = \alpha \pm i\beta$, Where $a = -b_1 / 2, b = \sqrt{-\Delta} / 2$.

The general solutions of (8) are

$$Y(t) = (C_1 \cos(\beta t) + C_2 \sin(\beta t)) \exp(\alpha t) + G / (1 - a)$$

If $\alpha > 0$, i.e. $b_1 < 0$, i.e. $1 < b$, the solutions are explosive oscillation

If $\alpha < 0$, i.e. $b_1 > 0$, i.e. $1 > b$, the solutions are damped oscillation,

We have a periodic solution only when $b = 1$.

Similarly, this continuous-time model also has four dynamic regimes. Its pattern regimes are shown in Figure 2. Compared with the discrete-time Samuelson's model, the only difference is the changing of the periodic border.

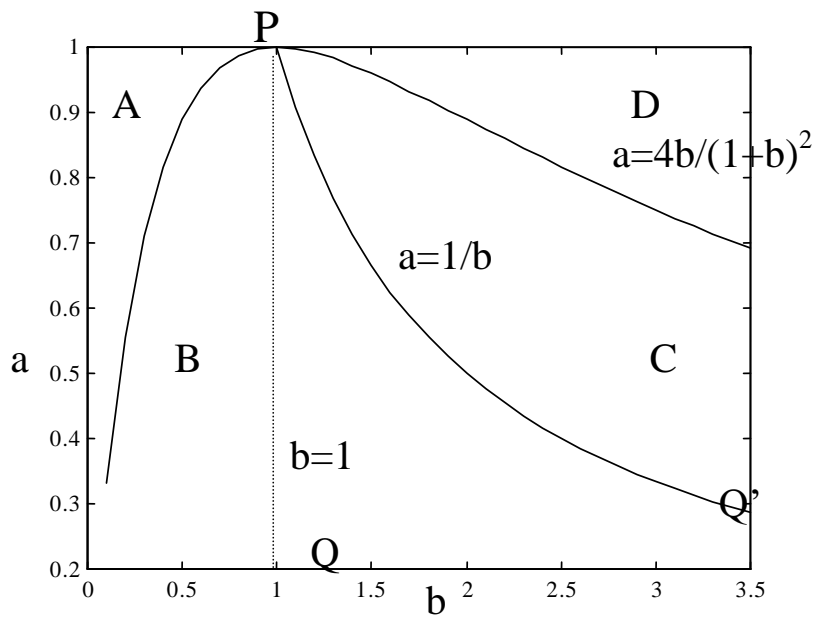


Figure 2. Continuous-time Samuelson's multiplier-accelerator diagram
The periodic boundary shifts from PQ' to PQ

4. The probability of return to equilibrium solution in Samuelson's multiplier-accelerator model

In the above analysis, we can find that the equilibrium solution of Samuelson's multiplier-accelerator model is the same as that of $G/(1-a)$ for both discrete time and continuous time.

In the following, we discuss the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model when the multiplier a and the accelerator b are in the range $0 < a < 1$ and $0 < b \leq T$. This probability is equal to the ratio of the area of the region returning to equilibrium solution to that of the whole region ($0 < a < 1$ and $0 < b \leq T$).

From Figure 1 and Figure 2, we can find that the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model is the same for both discrete time and continuous time, which is as follows.

When $0 < T \leq 1$, Prob = 100%.

When $T > 1$, $Prob = \{4[\ln(T+1) + 1/(T+1)] - 4\ln 2 - 1\} / T$.

When $T \rightarrow +\infty$, $Prob = 0$.

Note that when $T > 1$, $1/T < Prob < 1$.

It can be seen that the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model is a continuous function of T and monotonically decreasing (see Table 1).

Table 1. The probability of return to equilibrium solution in Samuelson's multiplier-accelerator model

T	1	1.7	15	2785	2860
Prob	100.00%	98.94%	50.45%	1.00%	0.98%

Where T is the length of the range of the accelerator b , and $Prob$ is the probability of return to equilibrium solution. When $0 < T \leq 1$, $Prob = 100\%$. When $T > 1$, $Prob = \{4[\ln(T+1) + 1/(T+1)] - 4\ln 2 - 1\} / T$. When $T \rightarrow +\infty$, $Prob = 0$.

Conclusion

In this paper, we study the continuous-time Samuelson's multiplier-accelerator model and compare this continuous-time model with its classical discrete-time model. We find that although time scales do not affect the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model, but time scales have an influence on the perfect symmetry of periodic motion.

The probability of return to equilibrium solution in Samuelson's multiplier-accelerator model is getting smaller with the increase of the range of the accelerator b (the length of the range is equal to T) when the multiplier a is greater than 0 and less than 1, regardless of discrete time or continuous time.

When $0 < T \leq 1$, the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model is 100%. The perfect symmetry of periodic motion of the continuous-time Samuelson's multiplier-accelerator model occurs at $b = 1$ (of course $T = 1$ at this time), while the perfect symmetry of the periodic motion of the discrete-time Samuelson's multiplier-accelerator model does not appear.

When $T > 1$, the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model is greater than $1/T$ and less than 1. The perfect symmetry of periodic motion of the continuous-time Samuelson's multiplier-accelerator model occurs at $b = 1$ and the perfect symmetry of the periodic motion of the discrete-time Samuelson's multiplier-accelerator model occurs at $a = 1/b$.

When T tends to $+\infty$, the probability of return to equilibrium solution in Samuelson's multiplier-accelerator model is astonishing zero.

Therefore, although the difference equations have large similarity with the differential equations, when abstracting economic phenomenon into mathematical models, the choice between the difference equation and the differential equation is not just a matter of convenience. We should carefully examine its empirical and theoretical foundation.

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